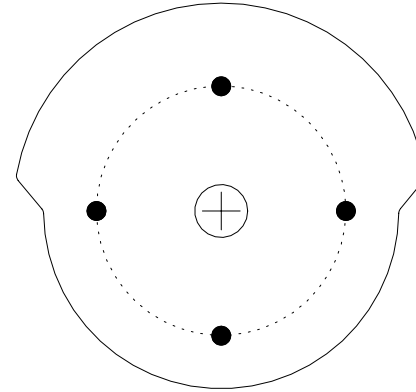


**Lower Cam. Engages First Micro Switch  
when on approximately Half Rudder.  
(Stops motor turning).**



**Upper Cam. Engages Second Micro Switch  
when on Full Rudder.  
(Motor runs in reverse).**

**These are the shapes of the two cams which I have made for Wyeforce.**

**These are only to be used as a guide as dimensions will vary depending on Micro Switch size, positions and servo used. Drawings NOT to scale.**

**Overall diameter 55 mm. Cut out diameter 47 mm (giving a 4 mm recess).**

**Round off all angles of cut outs to give a smooth flow for micro switch button.**

**My servo is a standard Futaba S 3003.  
Micro Switch size:16 mm wide x 28 mm long.**

**The fixing on the servo is a standard Futaba 4 arm cross,  
with 4 holes in each arm and the fixing holes shown are for this arm (33 mm pcd).**

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